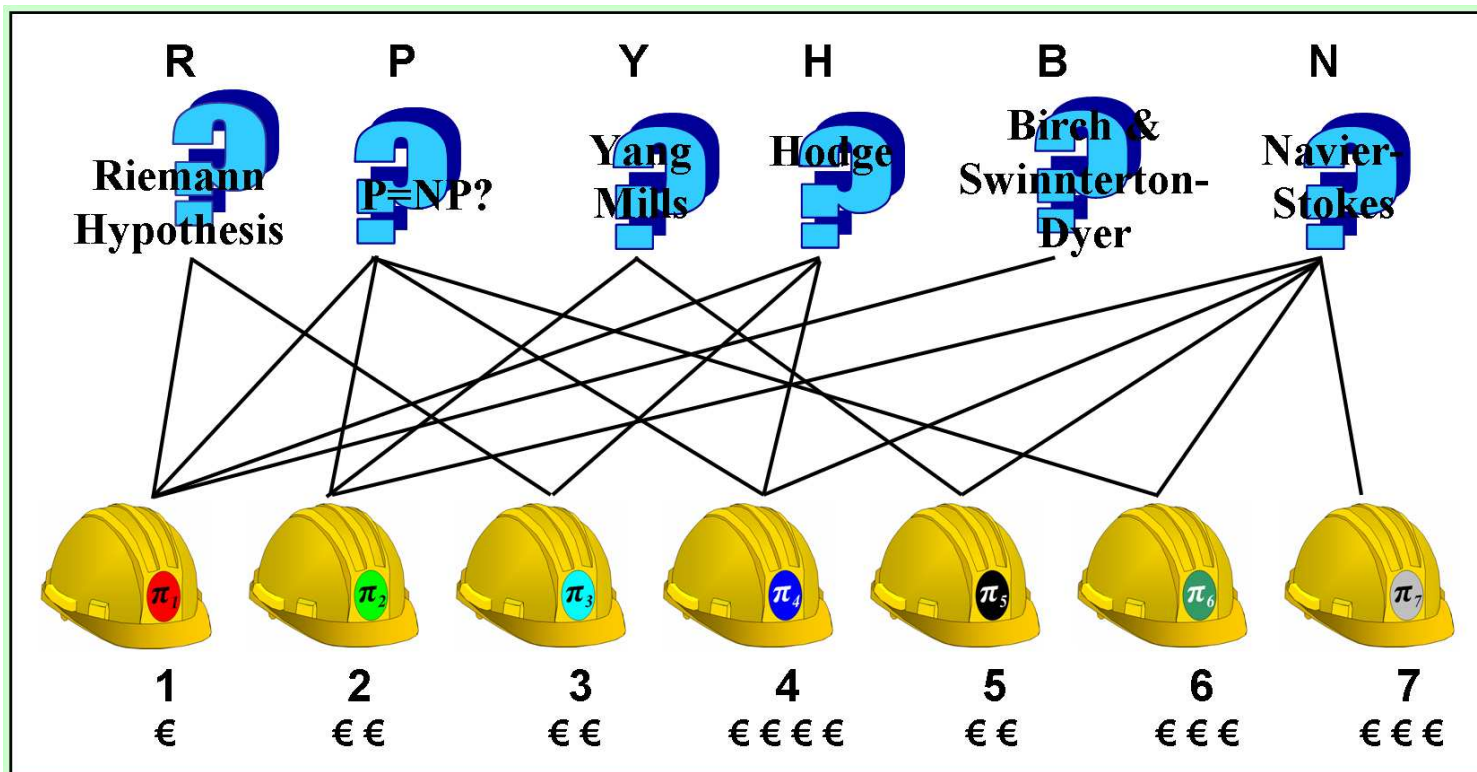


The Transversal Matroid Theorem Let E be a finite set and let $\mathcal{A} = \{A_i \mid i = 1, \dots, t\}$ be a family of subsets of E . Let \mathcal{T} denote the collection of partial transversals of \mathcal{A} , i.e. those subsets X of E having the property that each element of X may choose a distinct member of \mathcal{A} to which it belongs (thus if $X = \{x_1, \dots, x_k\}$ then there is a set $Y \subseteq \{1, \dots, t\}$ also having k elements, y_1, \dots, y_k , say, and satisfying $x_i \in A_{y_i}, i = 1, \dots, k$). Then \mathcal{T} forms the collection of independent sets of a matroid.



	1	2	3	4	5	6	7
R	r_1		r_3				
P	p_1	p_2		p_4		p_6	
Y		y_2			y_5		
H	h_1		h_3	h_4			
B	b_1						
N		n_2		n_4	n_5	n_6	n_7

The above incidence structure shows which workers (1, 2, ..., 7) may be assigned to which jobs (R, ..., N). The entries, r_1 , p_1 , etc., are *indeterminates*—they allow us to express any assignment as a ‘valueless’ product. For instance, the encircled assignment is expressed as $r_3 p_6 y_2 h_4 b_1 n_7$. This assignments gets all 6 jobs done at a cost of €15. But can it be done cheaper?

In the illustration above, each of the six remaining **Millennium Problems** of the **Clay Mathematics Institute** is to be assigned to a different subcontractor for Edsger Dijkstra’s fictitious Mathematics Inc. company. Obviously we want to solve all six problems as cheaply as possible! The *greedy* approach is to always to take the first, cheapest option: this would give us an assignment starting $r_1 p_2 h_3 y_5$. But now we are stuck because only subcontractor 1 can be assigned to problem B, and we used her for problem R; we will have to backtrack. Thus we cannot match up subcontractors to problems greedily. To say that partial transversals give a matroid is precisely to say that at least a cheapest maximal transversal *can* be selected greedily. That is, we can choose the cheapest subcontractors first and make the assignment to problems later. This may be more a difference in mathematics than in practice: it leaves open the question of how to build transversals *without* finding a matching.

This theorem was proved in the mid-1960s by Jack Edmonds and Delbert Ray Fulkerson in the USA and, independently (and also in an infinite version) by Leon Mirksy and Hazel Perfect at Sheffield University in the UK.

Web link: www.math.lsu.edu/~oxley/dominic.pdf. Read about Dijkstra’s Mathematics Inc. at www.cs.utexas.edu/~EWD/ (see e.g. no. 1224).

Further reading: *Introduction to Graph Theory, 4th Ed.*, by Robin Wilson, Longman, 1996, chapters 8 and 9 (look out for 5th Ed., due in 2010!)